

| Ref # | Hits | Search Query                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              | DBs                                                     | Default Operator | Plurals | Time Stamp       |
|-------|------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------|------------------|---------|------------------|
| S4    | 104  | ("5426545" "5740040" "5654619" "5911924" "6314333" "6473669" "4275605" "4327578" "4533991" "4950967" "5475291" "5515281" "5517099" "5710498" "5977732" "6470225" "4535372" "5272423" "4755876" "4300662" "4338659" "4540920" "4925312" "5385042" "5465612" "5495158" "5623189" "5699335" "6008609" "5325028" "5444349" "5675562" "6055217" "6249497" "4967291" "5015935" "5552943" "5663624" "5867456" "6178060" "6202796" "3586946" "4328450" "4328452" "4477750" "4488098" "4775903" "4816941" "4835633" "4891764").pn. | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | ON      | 2005/09/01 11:59 |
| S5    | 16   | S4 and (motor or actuator or machine) and load and accelerat\$4 and (subtract\$4 or differenc\$4 or differential) and filter\$4                                                                                                                                                                                                                                                                                                                                                                                           | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | ON      | 2005/09/01 12:00 |
| S6    | 16   | S4 and (motor or actuator or machine) and load and accelerat\$4 and ((subtract\$4 or differenc\$4 or differential) same (accelerat\$4 or speed or velocity)) and filter\$4                                                                                                                                                                                                                                                                                                                                                | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | ON      | 2005/09/01 12:00 |
| S7    | 13   | S4 and (motor or actuator or machine) and load and accelerat\$4 and ((subtract\$4 or differenc\$4 or differential) same (accelerat\$4 )) and filter\$4                                                                                                                                                                                                                                                                                                                                                                    | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | ON      | 2005/09/01 13:10 |
| S8    | 4    | S4 and (motor or actuator or machine) and load and accelerat\$4 and ((subtract\$4 or differenc\$4 or differential) near4 (accelerat\$4 )) and filter\$4                                                                                                                                                                                                                                                                                                                                                                   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | ON      | 2005/09/01 12:01 |
| S9    | 2    | S4 and (motor or actuator or machine) and load and accelerat\$4 and ((subtract\$4 or differenc\$4 or differential) near4 (accelerat\$4 )) and filter\$4 and ((lost or less\$4 or los\$4) near9 ( inertia\$4 or force or motion or movement))                                                                                                                                                                                                                                                                              | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | ON      | 2005/09/01 12:27 |
| S10   | 6    | S4 and accelerat\$4 and filter\$4 and ((lost or less\$4 or los\$4) near9 ( inertia\$4 or force or motion or movement))                                                                                                                                                                                                                                                                                                                                                                                                    | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | ON      | 2005/09/01 12:32 |
| S11   | 4    | S10 not S8                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | ON      | 2005/09/01 12:27 |
| S17   | 7    | accelerat\$4 and filter\$4 and ((lost or less\$4 or los\$4) near9 ( motion or movement)) and (motor or actuator or machine) and load and accelerat\$4 and ((subtract\$4 or differenc\$4 or differential) same (accelerat\$4 )) and (filter\$4 same (error or difference or differential )) and inertia\$4 and voltage and "318"/\$                                                                                                                                                                                        | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | ON      | 2005/09/01 12:37 |
| S18   | 22   | ((("6189836") or ("6041264") or ("5936158") or ("5896949") or ("5367238") or ("5623189") or ("5343132") or ("5175483") or ("4969757") or ("4578863") or ("3950683")).PN.                                                                                                                                                                                                                                                                                                                                                  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | OFF     | 2005/09/01 12:37 |
| S19   | 0    | S18 and accelerat\$4 and filter\$4 and ((lost or less\$4 or los\$4) near9 ( motion or movement)) and (motor or actuator or machine) and load and accelerat\$4 and ((subtract\$4 or differenc\$4 or differential) same (accelerat\$4 )) and (filter\$4 same (error or difference or differential )) and inertia\$4 and voltage                                                                                                                                                                                             | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | ON      | 2005/09/01 12:37 |
| S20   | 8    | S4 and (motor or actuator or machine) and load and accelerat\$4 and ((subtract\$4 or differenc\$4 or differential) same (accelerat\$4 )) and (filter\$4 same (differenc\$4 or differential or error))                                                                                                                                                                                                                                                                                                                     | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR               | ON      | 2005/09/01 13:19 |

|     |     |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |                                                         |    |    |                  |
|-----|-----|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------|----|----|------------------|
| S21 | 313 | (accelerat\$4 near4 error) and (filter\$4 same (accelerat\$4 near4 error))                                                                                                                                                                                                                                                                                                                                                                                                                                                | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 13:20 |
| S22 | 46  | (accelerat\$4 near4 error) and (filter\$4 same (accelerat\$4 near4 error)) and motor and load                                                                                                                                                                                                                                                                                                                                                                                                                             | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 13:20 |
| S23 | 22  | (accelerat\$4 near4 error) and (filter\$4 same (accelerat\$4 near4 error)) and motor and load and voltage and inertia                                                                                                                                                                                                                                                                                                                                                                                                     | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 13:21 |
| S24 | 20  | (accelerat\$4 near4 error) and (filter\$4 same (accelerat\$4 near4 error)) and motor and load and voltage and inertia and gain                                                                                                                                                                                                                                                                                                                                                                                            | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 13:21 |
| S25 | 14  | (accelerat\$4 near4 error) and (filter\$4 same (accelerat\$4 near4 error)) and motor and load and voltage and inertia and gain and ((subtract\$4 or differenc\$4 or differential) same (accelerat\$4 ))                                                                                                                                                                                                                                                                                                                   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 17:01 |
| S26 | 68  | (accelerat\$4 near4 (subtract\$4 or differenc\$4 )) and (filter\$4 ) and motor and load and voltage and inertia and gain                                                                                                                                                                                                                                                                                                                                                                                                  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 18:49 |
| S27 | 104 | ("5426545" "5740040" "5654619" "5911924" "6314333" "6473669" "4275605" "4327578" "4533991" "4950967" "5475291" "5515281" "5517099" "5710498" "5977732" "6470225" "4535372" "5272423" "4755876" "4300662" "4338659" "4540920" "4925312" "5385042" "5465612" "5495158" "5623189" "5699335" "6008609" "5325028" "5444349" "5675562" "6055217" "6249497" "4967291" "5015935" "5552943" "5663624" "5867456" "6178060" "6202796" "3586946" "4328450" "4328452" "4477750" "4488098" "4775903" "4816941" "4835633" "4891764").pn. | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 18:54 |
| S28 | 8   | S27 and (accelerat\$4) and (subtract\$4 or differenc\$4 ) and (filter\$4 ) and motor and load and voltage and inertia and gain                                                                                                                                                                                                                                                                                                                                                                                            | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 19:33 |
| S29 | 3   | S27 and (accelerat\$4) and (deviat\$4) and (filter\$4 ) and motor and load and voltage and inertia and gain                                                                                                                                                                                                                                                                                                                                                                                                               | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 19:34 |
| S30 | 1   | 318/276 and (accelerat\$4) and (deviat\$4) and (filter\$4 ) and motor and load and voltage and inertia and gain                                                                                                                                                                                                                                                                                                                                                                                                           | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 19:38 |
| S31 | 2   | 318/276 and (accelerat\$4) and (deviat\$4) and motor and load and voltage and inertia and gain                                                                                                                                                                                                                                                                                                                                                                                                                            | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 19:42 |
| S32 | 6   | ("4808895").URPN.                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         | USPAT                                                   | OR | ON | 2005/09/01 19:42 |
| S33 | 0   | S32 and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and motor and load and voltage and inertia and gain                                                                                                                                                                                                                                                                                                                                                                                                 | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 19:43 |

|     |      |                                                                                                                                                                                                                                                                                                     |                                                         |    |     |                  |
|-----|------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------|----|-----|------------------|
| S34 | 4    | 318/276 and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and motor and load and voltage and inertia and gain                                                                                                                                                                       | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2005/09/01 19:45 |
| S35 | 1838 | (318/268-279).CCLS.                                                                                                                                                                                                                                                                                 | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | OFF | 2005/09/01 19:45 |
| S36 | 0    | 318/277 and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and motor and load and voltage and inertia and gain                                                                                                                                                                       | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2005/09/01 19:46 |
| S37 | 0    | 318/277 and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and motor and load and voltage and (friction\$4 or inertia\$4) and gain                                                                                                                                                   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2005/09/01 19:46 |
| S38 | 2    | 318/278 and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and motor and load and voltage and (friction\$4 or inertia\$4) and gain                                                                                                                                                   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2005/09/01 19:50 |
| S39 | 0    | 318/279 and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and motor and load and voltage and (friction\$4 or inertia\$4) and gain                                                                                                                                                   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2005/09/01 19:50 |
| S40 | 5    | 318/274 and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and motor and load and voltage and (friction\$4 or inertia\$4) and gain                                                                                                                                                   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2005/09/01 19:54 |
| S41 | 13   | 318/271 and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and motor and load and voltage and (friction\$4 or inertia\$4) and gain                                                                                                                                                   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2005/09/01 19:54 |
| S42 | 11   | 318/271 and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and motor and load and voltage and (friction\$4 or inertia\$4) and gain\$2 and (accelerat\$4 same (deviat\$4 or subtract\$4 or differenc\$4))                                                                             | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2005/09/01 20:00 |
| S43 | 5    | 318/270 and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and motor and load and voltage and (friction\$4 or inertia\$4) and gain\$2 and (accelerat\$4 same (deviat\$4 or subtract\$4 or differenc\$4))                                                                             | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2005/09/01 20:01 |
| S44 | 47   | ((accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4)).ab. and motor and load and voltage and (friction\$4 or inertia\$4) and gain\$2 and (accelerat\$4 same (deviat\$4 or subtract\$4 or differenc\$4))                                                                                   | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2005/09/01 20:03 |
| S45 | 47   | ((accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4)).ab. and motor and load and voltage and (friction\$4 or inertia\$4) and gain\$2 and (accelerat\$4 same (deviat\$4 or subtract\$4 or differenc\$4)) and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4)                 | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2005/09/05 15:10 |
| S46 | 28   | ((accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4)).ab. and motor and load and voltage and (friction\$4 or inertia\$4) and gain\$2 and (accelerat\$4 same (deviat\$4 or subtract\$4 or differenc\$4)) and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and (filter\$4) | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON  | 2005/09/01 20:07 |

|     |      |                                                                                                                                                                                                                                                                                                                  |                                                         |    |    |                  |
|-----|------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------|----|----|------------------|
| S47 | 6    | (rehm near4 thomas) and acceleration                                                                                                                                                                                                                                                                             | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 20:04 |
| S48 | 1    | (rehm near4 thomas) and motor and load and voltage and (friction\$4 or inertia\$4) and gain\$2 and (accelerat\$4 same (deviat\$4 or subtract\$4 or differenc\$4)) and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and (filter\$4 )                                                             | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 20:06 |
| S49 | 1    | (rehm near4 thomas) and motor and load and voltage and (friction\$4 or inertia\$4) and gain\$2 and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and (filter\$4 )                                                                                                                                | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 20:06 |
| S50 | 3    | (rehm near4 thomas) and motor and load and voltage and (friction\$4 or inertia\$4) and gain\$2 and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4)                                                                                                                                                 | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 20:06 |
| S51 | 21   | ((accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4)).ab. and motor and load and voltage and (friction\$4 or inertia\$4) and gain\$2 and (accelerat\$4 near9 (deviat\$4 or subtract\$4 or differenc\$4)) and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and (filter\$4 )            | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 20:08 |
| S52 | 10   | ((accelerat\$4) near9 (deviat\$4 or subtract\$4 or differenc\$4)).ab. and motor and load and voltage and (friction\$4 or inertia\$4) and gain\$2 and (accelerat\$4 near9 (deviat\$4 or subtract\$4 or differenc\$4)) and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and (filter\$4 )          | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 20:23 |
| S53 | 16   | ((accelerat\$4) near9 (deviat\$4 or subtract\$4 or differenc\$4 or error)).ab. and motor and load and voltage and (friction\$4 or inertia\$4) and gain\$2 and (accelerat\$4 near9 (deviat\$4 or subtract\$4 or differenc\$4)) and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and (filter\$4 ) | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 20:40 |
| S54 | 19   | ("4477757"   "4808901"   "4921365"   "4967293"   "4990840"   "5003238"   "5250880").PN. OR ("5416397").URPN.                                                                                                                                                                                                     | US-PGPUB;<br>USPAT;<br>USOCR                            | OR | ON | 2005/09/01 20:22 |
| S55 | 0    | S54 and motor and load and voltage and (friction\$4 or inertia\$4) and gain\$2 and (accelerat\$4 near9 (deviat\$4 or subtract\$4 or differenc\$4)) and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4) and (filter\$4 )                                                                            | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 20:22 |
| S56 | 0    | S54 and motor and load and voltage and (friction\$4 or inertia\$4) and gain\$2 and (accelerat\$4 near9 (deviat\$4 or subtract\$4 or differenc\$4)) and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4)                                                                                             | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 20:22 |
| S57 | 6    | S53 not S52                                                                                                                                                                                                                                                                                                      | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 20:23 |
| S58 | 23   | ((accelerat\$4) near9 (deviat\$4 or subtract\$4 or differenc\$4 or error)).ab. and motor and load and voltage and (friction\$4 or inertia\$4) and gain\$2 and (accelerat\$4 near9 (deviat\$4 or subtract\$4 or differenc\$4)) and (accelerat\$4) and (deviat\$4 or subtract\$4 or differenc\$4)                  | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 20:40 |
| S59 | 7    | S58 not S53                                                                                                                                                                                                                                                                                                      | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 20:54 |
| S60 | 6338 | (gain near4 ("40"))                                                                                                                                                                                                                                                                                              | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 20:55 |

|     |     |                                                                                                                                                                   |                                                         |    |    |                  |
|-----|-----|-------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------------------------------------|----|----|------------------|
| S61 | 11  | ((gain near4 ("40")) same inertia)                                                                                                                                | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 21:41 |
| S62 | 12  | ((gain near4 ("50")) same inertia)                                                                                                                                | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 20:59 |
| S63 | 10  | S62 not S61                                                                                                                                                       | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 21:07 |
| S64 | 945 | ((speed or velocity) near4 (fault or error)) near4 constant)                                                                                                      | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 21:08 |
| S65 | 74  | ((speed or velocity) near4 (fault or error)) near4 (time adj3 constant))                                                                                          | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 21:08 |
| S66 | 8   | ((speed or velocity) near4 (fault or error)) near4 (time adj3 constant)) and (((acceleration) near4 (fault or error)) near4 (time adj3 constant))                 | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 21:14 |
| S67 | 15  | ((speed or velocity) near9 (fault or error)) near9 (time adj3 constant)) and (((acceleration) near9 (fault or error)) near9 (time adj3 constant))                 | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 21:16 |
| S68 | 7   | S67 not S66                                                                                                                                                       | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 21:14 |
| S69 | 231 | ((speed or velocity) near9 (fault or error)) near9 (time )) and (((acceleration) near9 (fault or error)) near9 (time ))                                           | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 21:16 |
| S70 | 190 | ((speed or velocity) near9 (fault or error)) near9 (time )) same (((acceleration) near9 (fault or error)) near9 (time )) )                                        | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 21:17 |
| S71 | 101 | ((speed or velocity) near9 (fault or error)) near9 (time )) same (((acceleration) near9 (fault or error)) near9 (time )) ) and motor                              | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 21:17 |
| S72 | 42  | ((speed or velocity) near9 (fault or error)) near9 (time )) same (((acceleration) near9 (fault or error)) near9 (time )) ) and motor and (inertia\$4 or friction) | US-PGPUB;<br>USPAT;<br>EPO; JPO;<br>DERWENT;<br>IBM_TDB | OR | ON | 2005/09/01 21:18 |